

Estimation of the benefits of remote- sensing profilers for sustainable energy applications

Tatiana Nomokonova, Ulrich Löhnert,

Tobias Necker*, Philipp Griewank, Martin Weissmann

* in collaboration with RIKEN, R-CCS, Japan



„Climate Monitoring and Diagnostics
(Cologne/Bonn)“



Motivation

- Networks of ground-based instruments planned
- Model output with 1000 ensembles available for sensitivity analysis
- No real observations are required
- Impact on short-term forecast for renewable energy applications?
- Our first attempt: wind lidar network for low-level wind forecast

Question for this study

- How much improvement can a Doppler wind lidar network add relative to conventionally assimilated surface observations?

Input data

Model

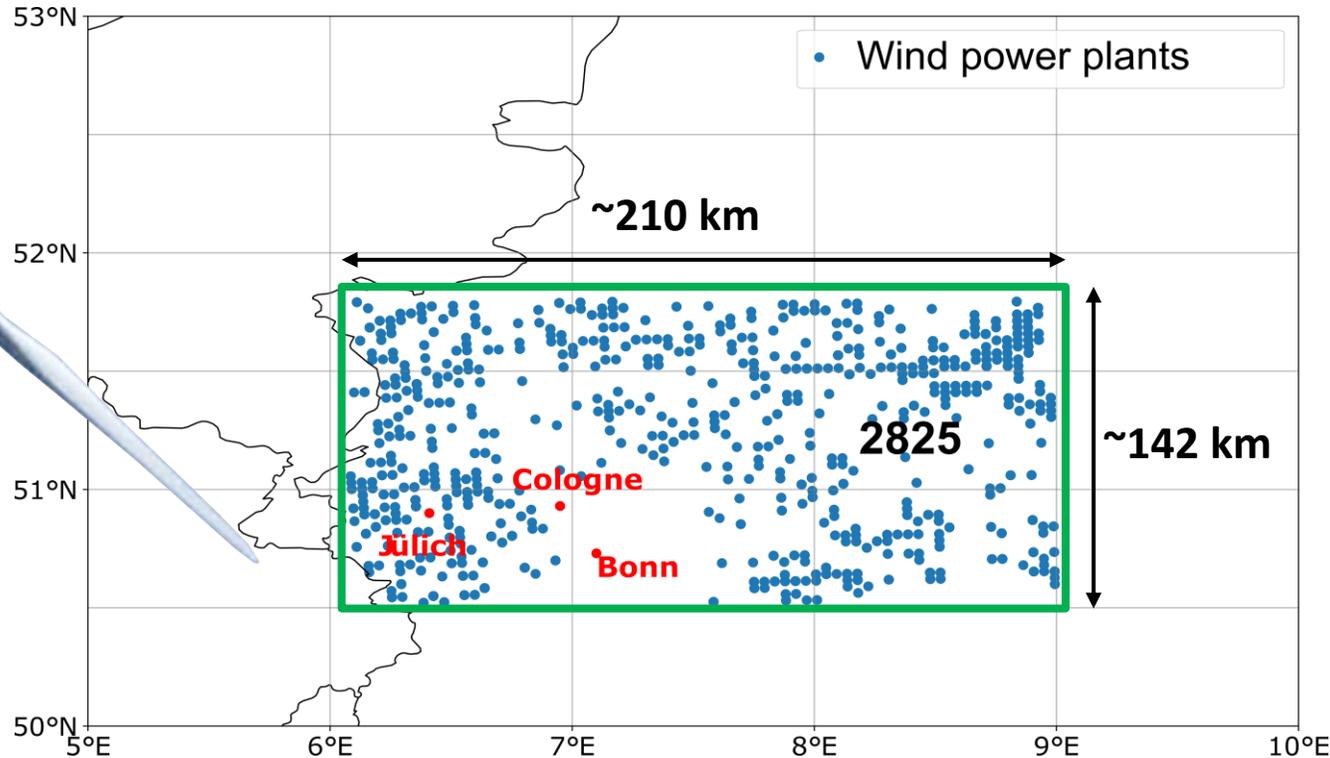
- Regional climate / weather forecasting model
SCALE-RM
- **1000-member ensemble** (Necker et. al, 2020)
- Over Germany, space resolution **3 km**
- **Model domain:** 352 x 250 grid points centered over Germany
- **Every 10th grid point** of model-output used for the analysis to reduce the state space

Simulated observations

- **Wind profiles** from hypothetical **Doppler lidars**
- Analysis of **5 levels** (model output): (80, 429, 1062, 1853, and 2845 m)



Focus of the experiment: RRA with wind parks



Wind power parks (2019):

2825 wind power plants within RRA

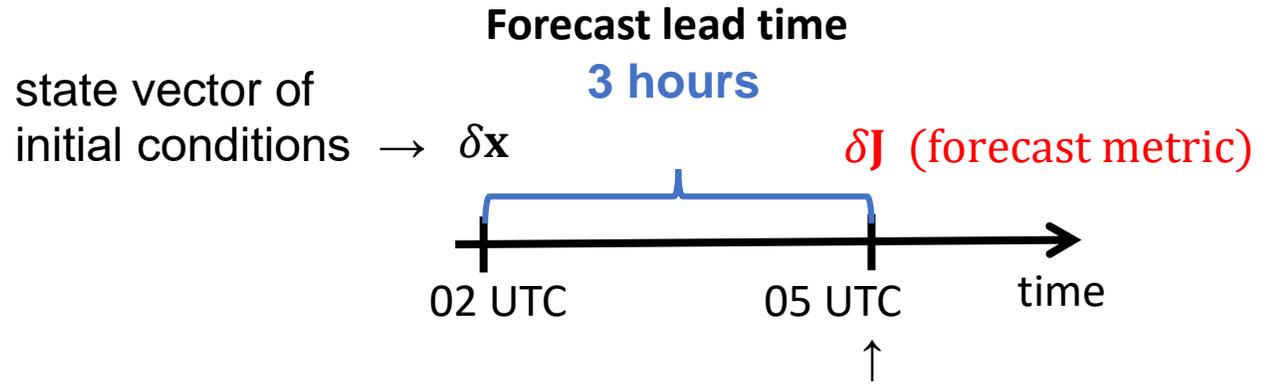
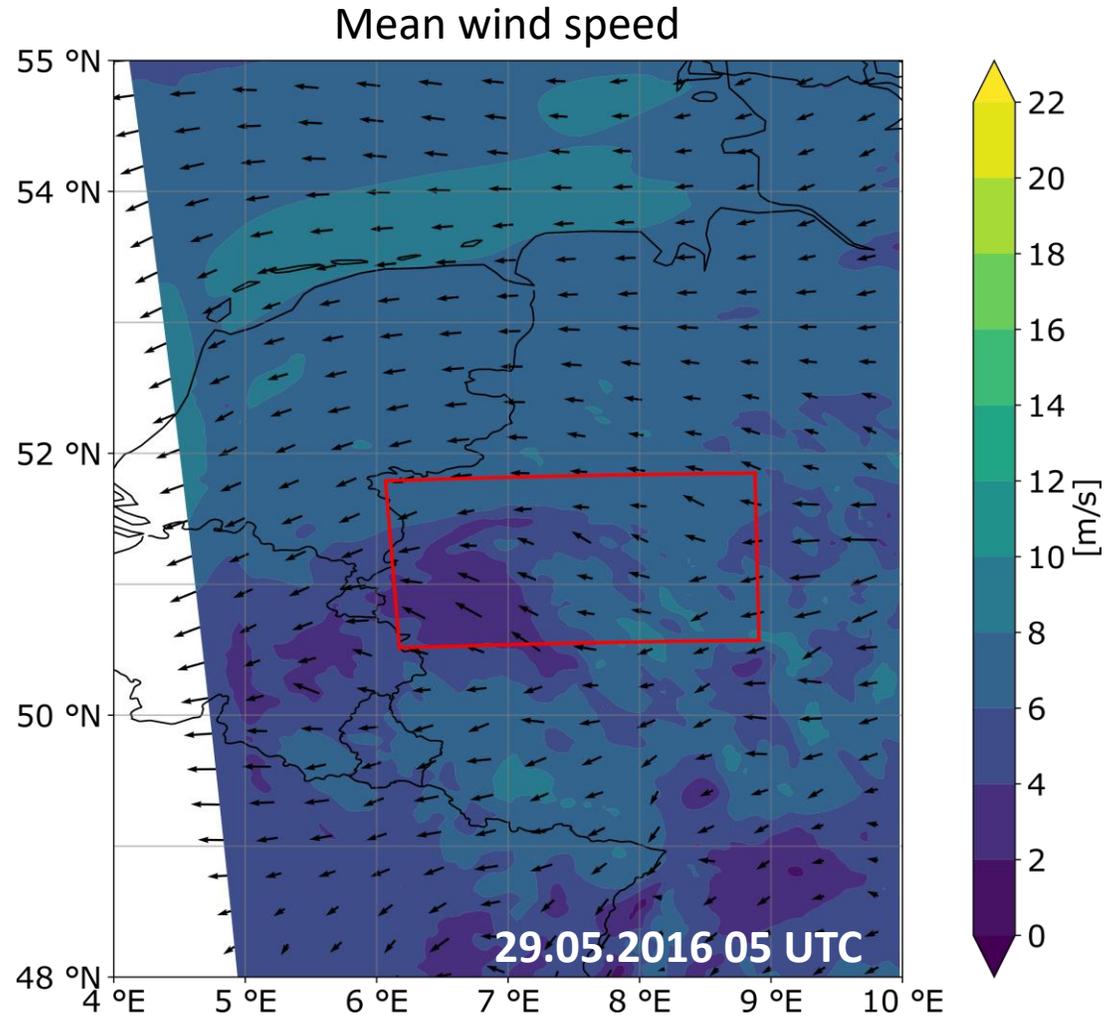
Maximum output of RRA power stations:

~5.1 GW (7.4 %)

Total wind power in Germany ~ 69.23 GW

Data of wind power location were obtained by personal communication with Lukas Schmidt and <https://github.com/OpenEnergyPlatform/open-MaStR>

Forecast metric over RRA: wind speed at 80 m



Domain averaged wind speed over RRA at 80 m
(typical hub-height of wind turbines)

$$\text{Sensitivity} = \text{cov}(\delta \mathbf{J}, \delta \mathbf{x}) \mathbf{B}^{-1}$$

$$\mathbf{B} = \{\delta \mathbf{x} \delta \mathbf{x}^T\}$$

Ancell and Hakim, 2007

Method: ensemble sensitivity to estimate variance reduction

1) Forecast variance reduction: $\delta\sigma^2 = \text{Sensitivity} (\mathbf{A}_{\text{updated}} - \mathbf{B}) (\text{Sensitivity})^T$

Method: ensemble sensitivity to estimate variance reduction

1) Forecast variance reduction: $\delta\sigma^2 = \text{Sensitivity} (\mathbf{A}_{\text{updated}} - \mathbf{B}) (\text{Sensitivity})^T$

2) Reduction of background covariance matrixes (Ansell and Hakim, 2007):

$$(\mathbf{A}_{\text{updated}} - \mathbf{B}) = -\mathbf{KHB} = -\underbrace{(\mathbf{L} \circ \mathbf{B}) \mathbf{H}^T (\mathbf{H} (\mathbf{L} \circ \mathbf{B}) \mathbf{H}^T + \mathbf{R})^{-1}}_{\text{Kalman gain (K)}} \mathbf{H} \mathbf{B},$$

\mathbf{B} – state covariance matrix before added wind lidars;
 \mathbf{H} – forward operator; \mathbf{R} – error covariance matrix;

$\mathbf{A}_{\text{updated}}$ – updated state covariance matrix;
◦ Schur product; \mathbf{L} – localization matrix

Method: ensemble sensitivity to estimate variance reduction

1) Forecast variance reduction: $\delta\sigma^2 = \text{Sensitivity} (\mathbf{A}_{\text{updated}} - \mathbf{B}) (\text{Sensitivity})^T$

2) Reduction of background covariance matrixes (Ansell and Hakim, 2007):

$$(\mathbf{A}_{\text{updated}} - \mathbf{B}) = -\mathbf{KHB} = -\underbrace{(\mathbf{L} \circ \mathbf{B}) \mathbf{H}^T (\mathbf{H} (\mathbf{L} \circ \mathbf{B}) \mathbf{H}^T + \mathbf{R})^{-1}}_{\text{Kalman gain (K)}} \mathbf{H} \mathbf{B},$$

\mathbf{B} – state covariance matrix before added wind lidars;
 \mathbf{H} – forward operator;

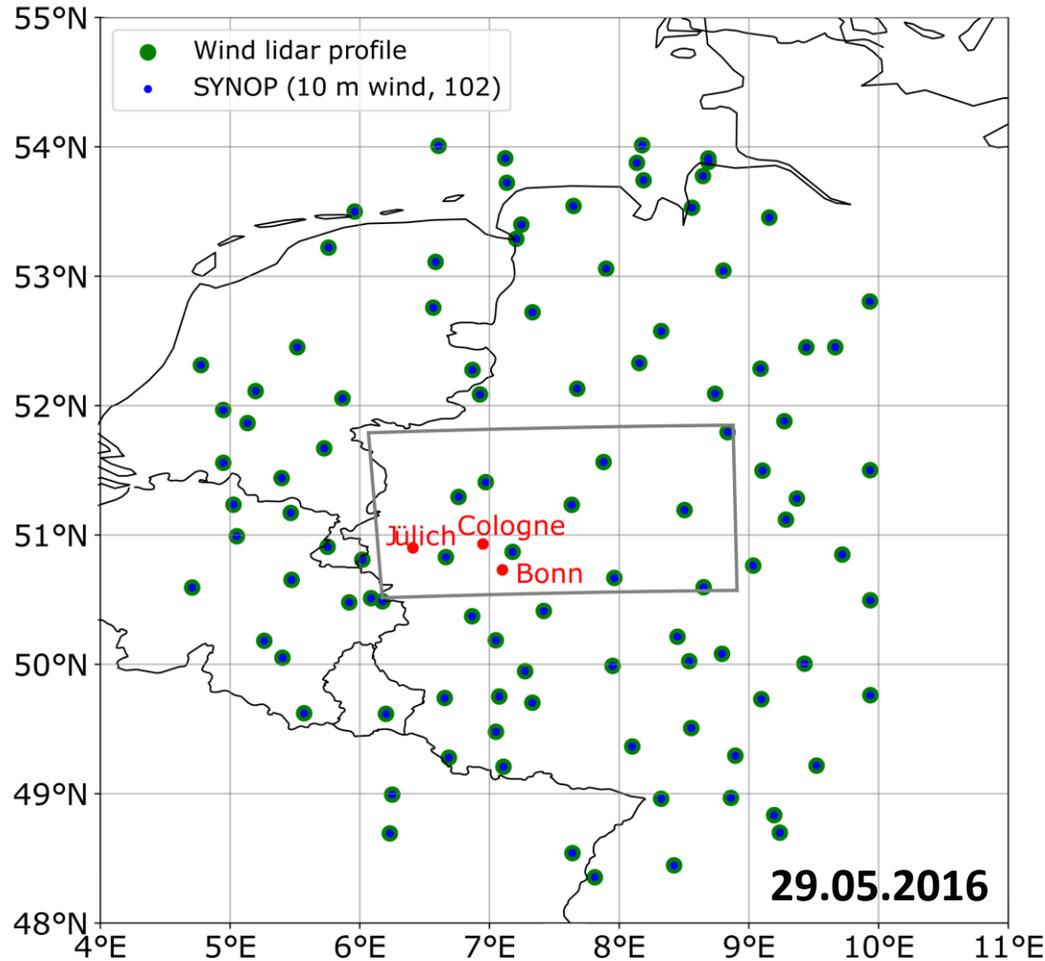
$\mathbf{A}_{\text{updated}}$ – updated state covariance matrix;
 \circ – Schur product; \mathbf{L} – localization matrix

3) $\text{Sensitivity} = (\mathbf{B}^T \mathbf{B} + \alpha^2 \mathbf{I})^{-1} \mathbf{B}^T (\text{cov}(\delta\mathbf{J}, \delta\mathbf{x}^T))^T$ $\delta\mathbf{J}$ – forecast metric,
 $\delta\mathbf{x}$ – state vector of initial conditions

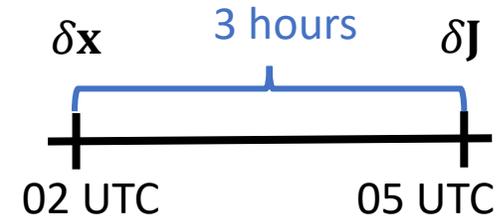
Sensitivity is regularized by Tikhonov method ($\alpha = 0.1$)

Experimental setup based on SCALE-RM 1000 ensemble

Potential wind lidar network to improve 3-hour forecasted low-level wind (at 05 UTC):



Coordinates of the SYNOP stations were provided by Elisabeth Bauernschubert



1) Target: domain averaged 80 m wind speed over RRA
(typical hub-height of wind turbines)

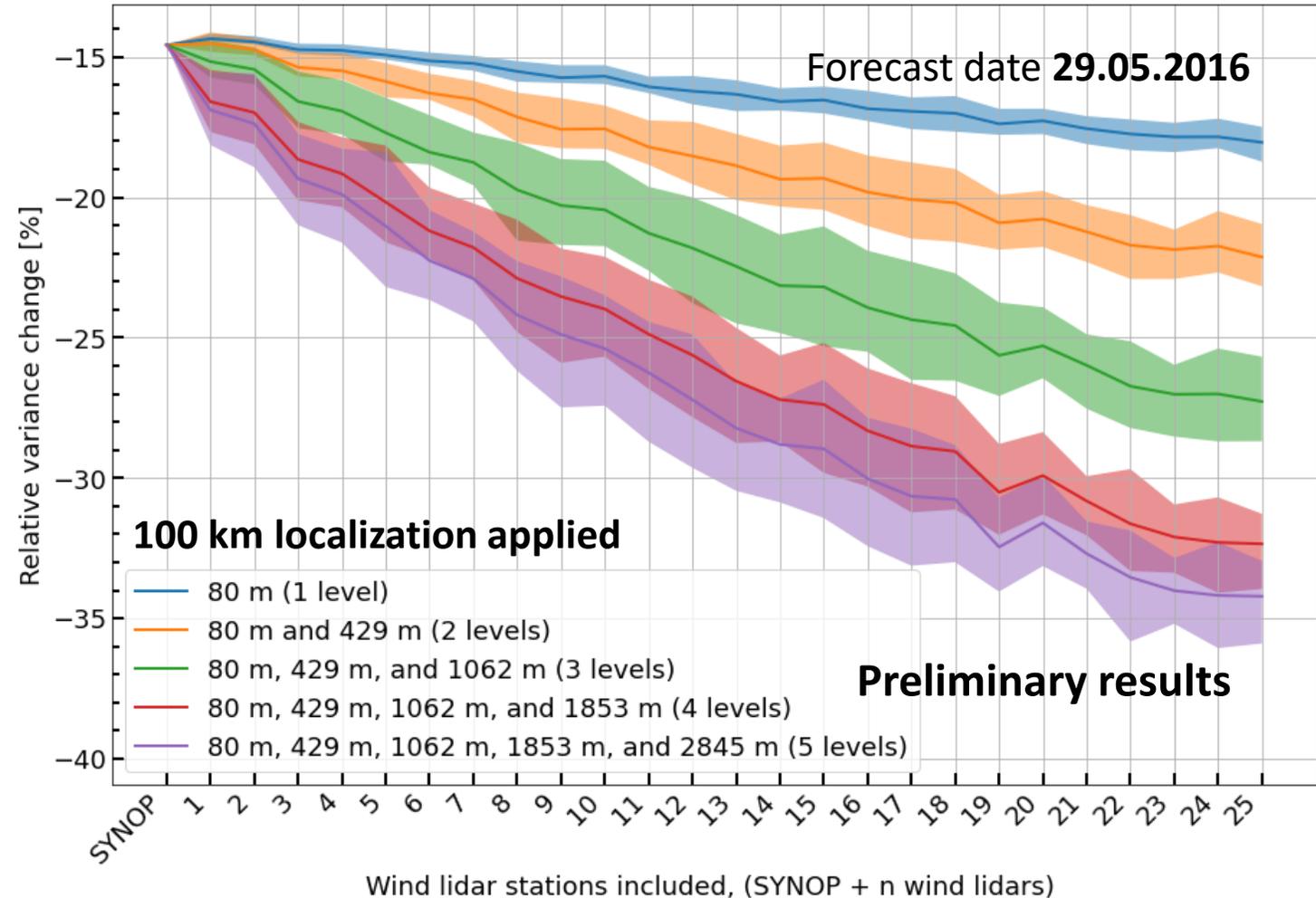
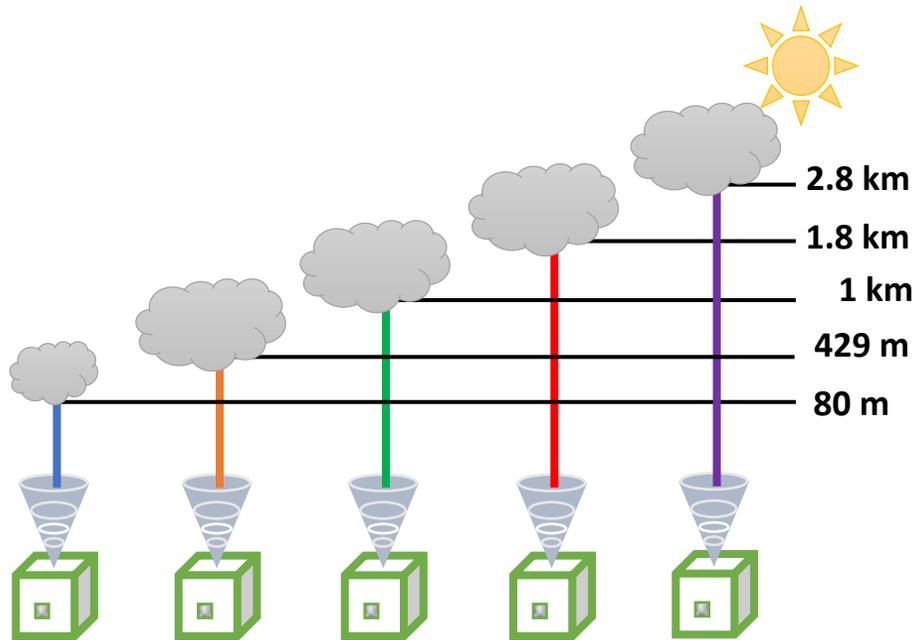
2) Incorporated observations:

- wind speed at 10 m (SYNOP stations)
- wind speed profiles (up to 25 random stations)
- 1 to 5 levels included: 80, 429, 1062, 1853, 2845 m
- 50 repetitions (random choice of stations)

NOTE: this study considers only one day (29.05.2016)

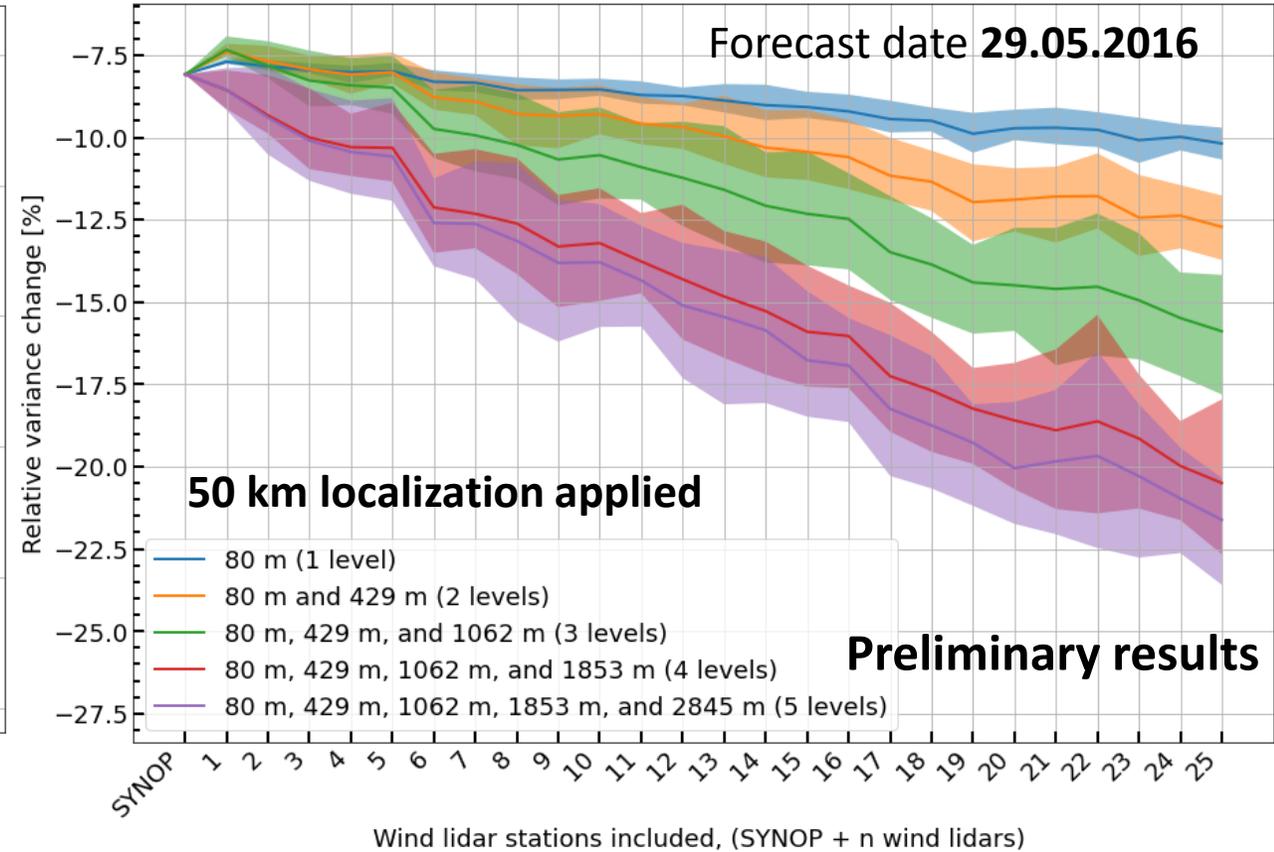
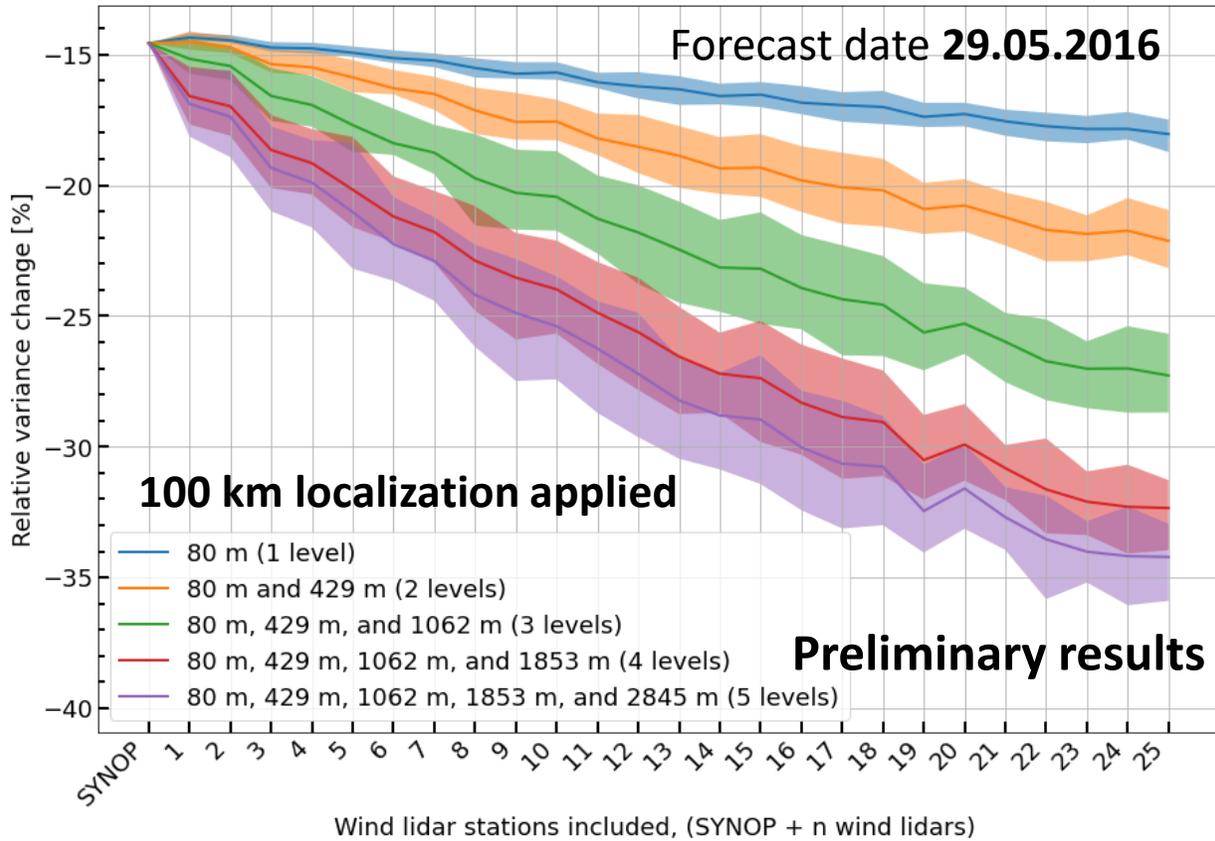
Variance reduction: with applied localizations of 100 km

Potential wind lidar observations:



- **25 wind lidars** → **1.2 - 2.5x** improvement
- The benefit depends on different wind lidar ranges, influenced by ABL conditions

Variance reduction: with applied localizations of 100 and 50 km

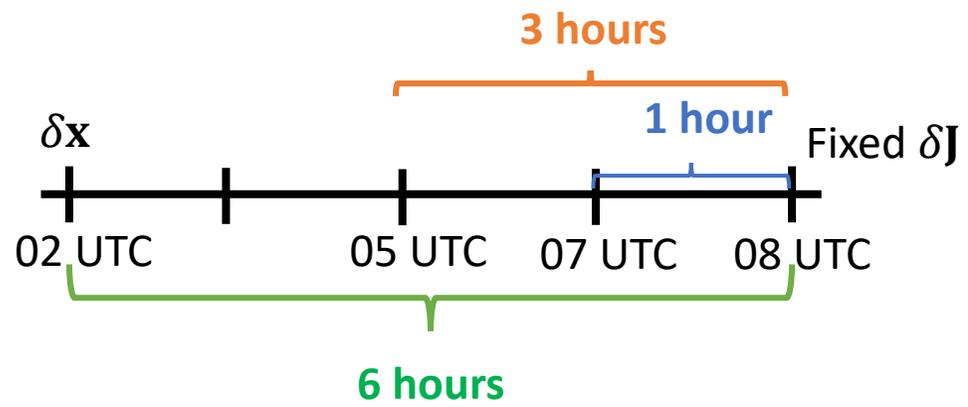
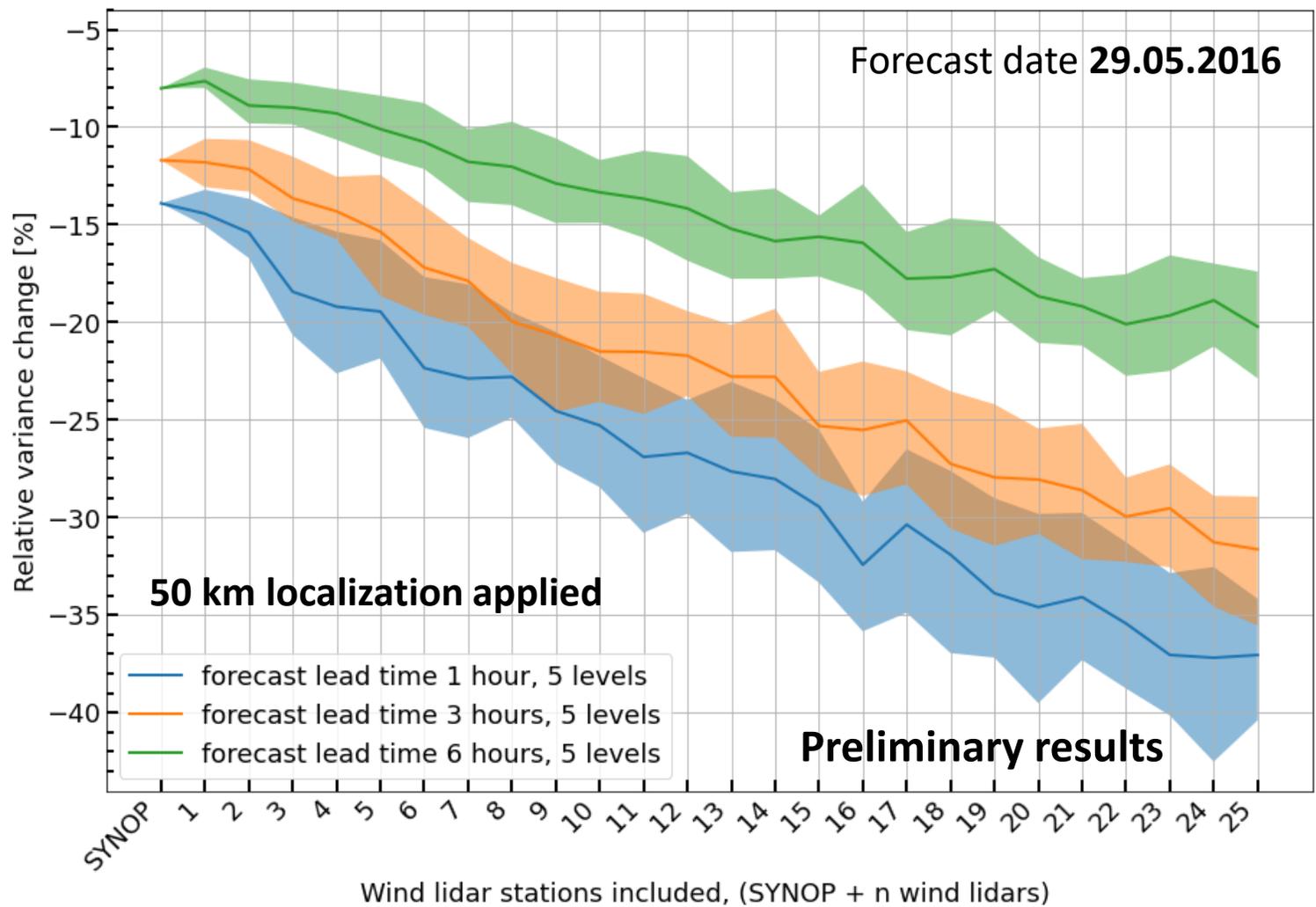


An additional relative change with respect to SYNOP:

25 wind lidars → 1.2 - 2.5x improvement (L = 100 km)

25 wind lidars → 1.5 - 3x improvement (L = 50 km)

Variance reduction: for different lead time (localization 50 km)



- As expected more improvements for the smaller lead time (**25 wind lidars** → **3x** improvement with respect to SYNOP)
- Benefits from Doppler lidar network even for a **6 hour** lead time (**25 wind lidars** → **2.8x** improvement with respect to SYNOP)

Summary

- Doppler wind lidars (spread out inside and around RRA) show the potential to improve the low-level wind forecast
- **25 wind lidars** → **1.2 - 3x** improvement (with respect to SYNOP stations only) depending on localization value and different wind lidar ranges, influenced by ABL conditions
- As expected more improvements for the smaller lead time (**25 wind lidars** → **3x** improvement with respect to SYNOP). Benefits from Doppler wind lidar network even for a 6 hour lead time

Outlook

- Extend the analysis to include more available forecasts and days
- Investigate potential impact of ground-based microwave radiometers on cloud cover and predicted solar power production

