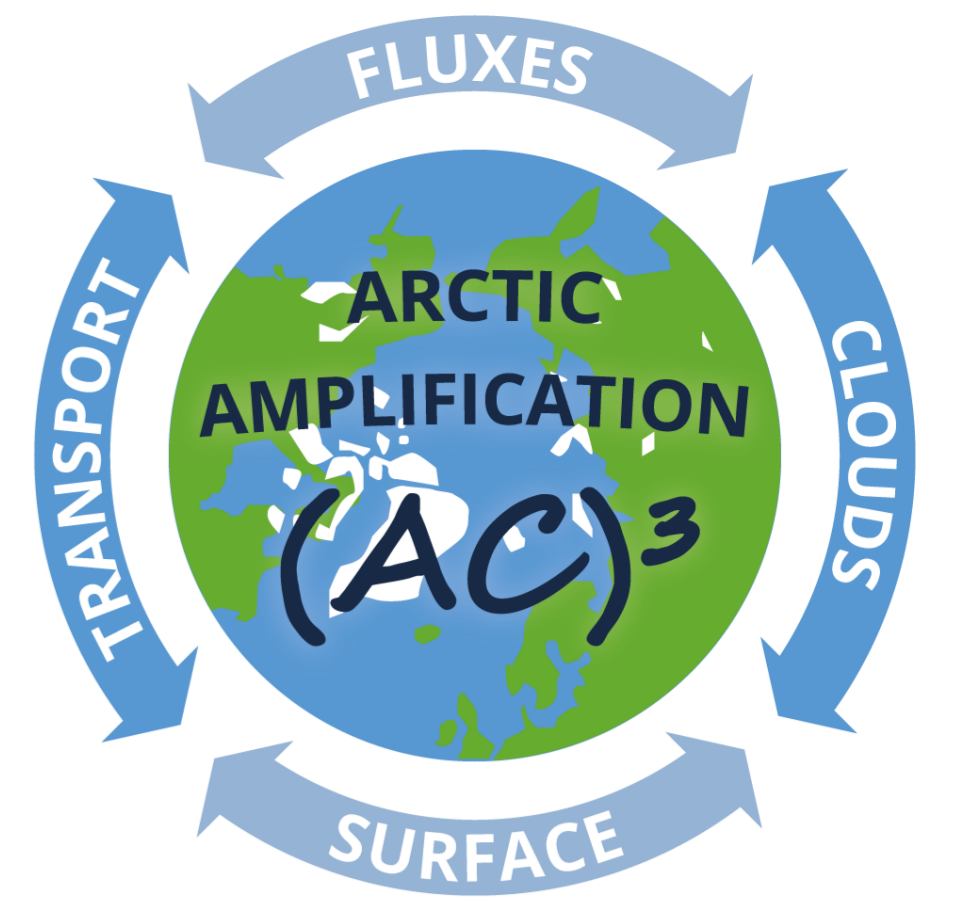


Removal of artificial echoes and coordinate transformation of aircraft radar measurements in the Arctic

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Introduction

The **Microwave Radar/radiometer for Arctic Clouds (MiRAC)** has been flown on the **Polar 5** aircraft during the **ACLOUD** campaign to characterize Arctic clouds in May and June 2017.

To the best of our knowledge it is the first time that a **Frequency-Modulated Continuous Wave (FMCW)** radar is used for down-looking cloud observations. The inclination is 25° with respect to nadir.



Fig. 1: MiRAC mounted in the belly pod between the wings below Polar 5. During flight Mirac's inclination is 25° with respect to nadir view.

MiRAC

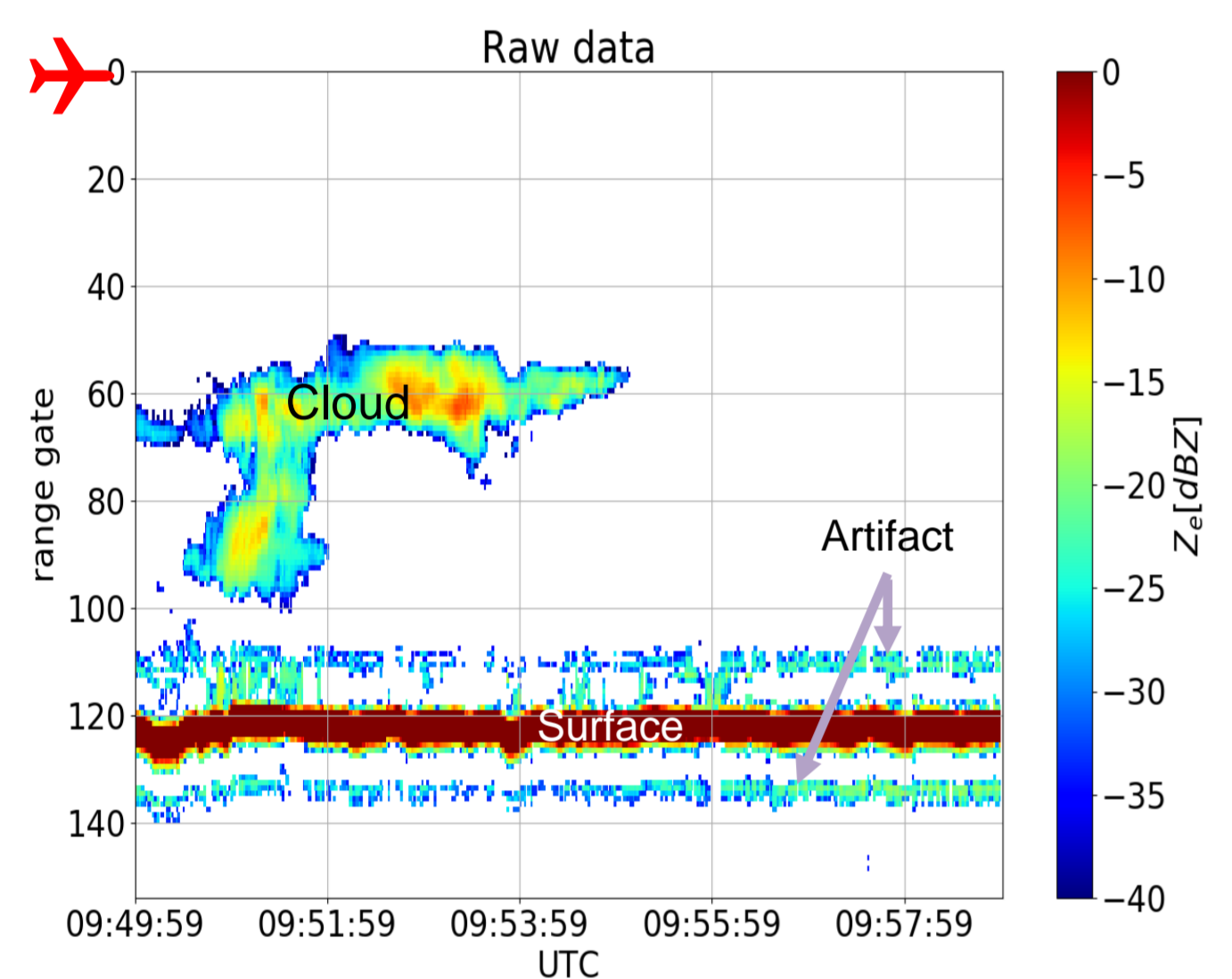
MiRAC performs active (radar reflectivity Z , Doppler velocity v_D) and passive (brightness temperature T_B) measurements:

- The Z -profile is influenced by the strong surface reflection and radar processor artifacts. The artifacts near the surface likely occur due to the special measurement technique (FMCW-Radar), which includes two Fourier transforms (Küchler et al., 2017). The radar calibration was also thoroughly checked.
- The use of v_D is difficult due to aircraft motion and unknown total wind velocity.
- T_B will be used to retrieve the **Liquid Water Path LWP** and **Integrated Water Vapor IWV**.

FMCW-Radar: 94 GHz (25°)

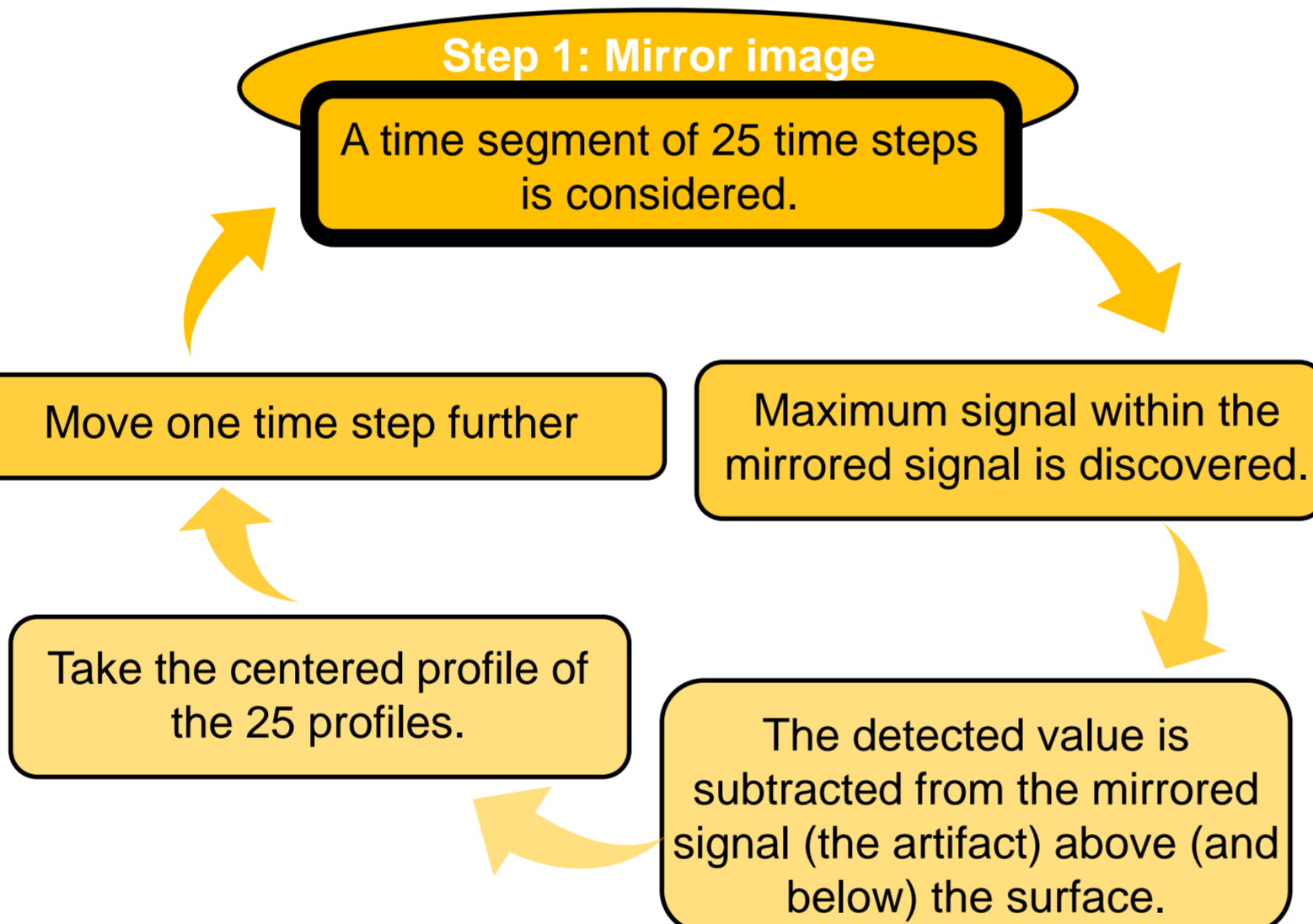
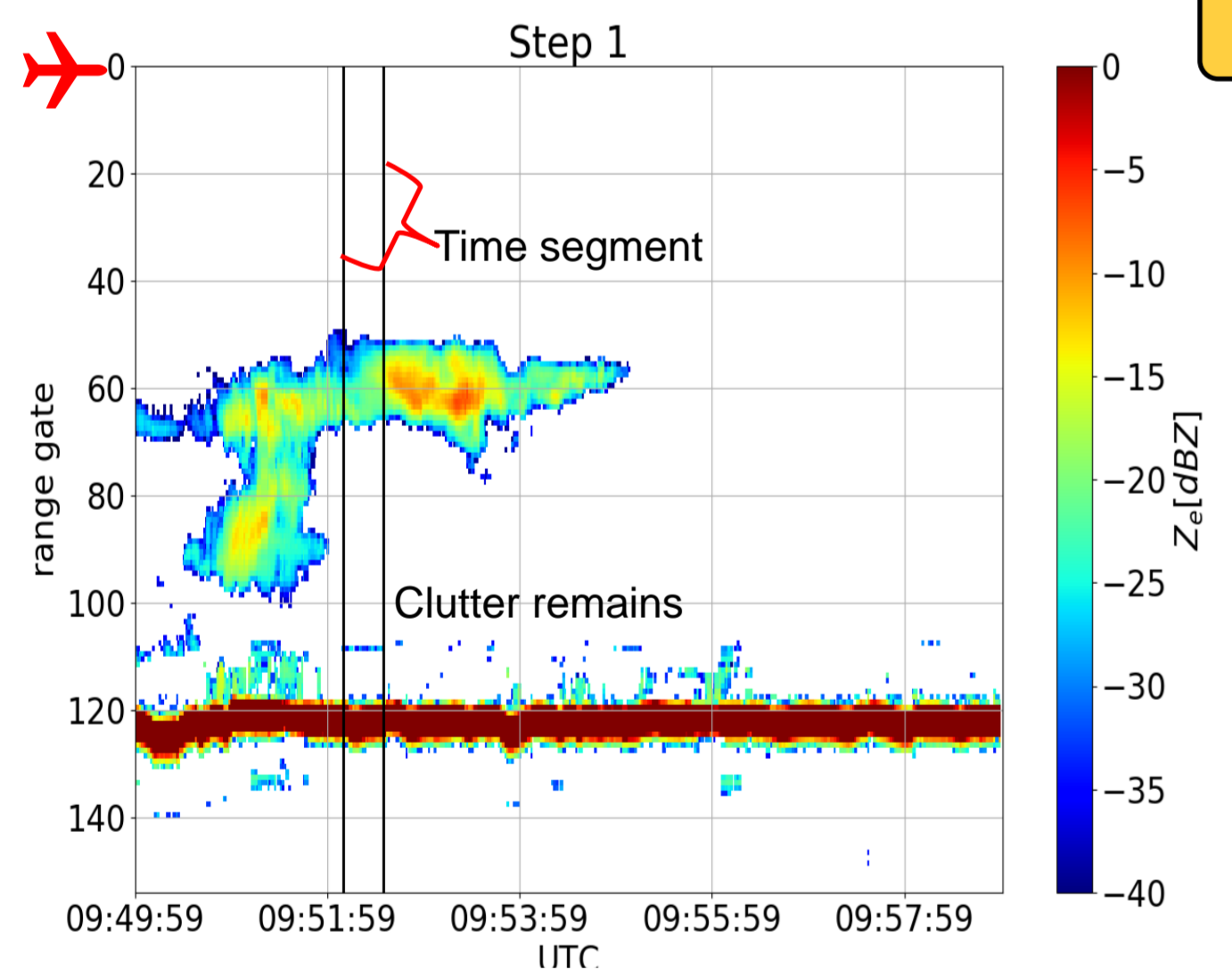
Radiometer: 89 GHz (25°), 6 x 183, 240, 340 GHz (nadir)

Removal of artificial echoes

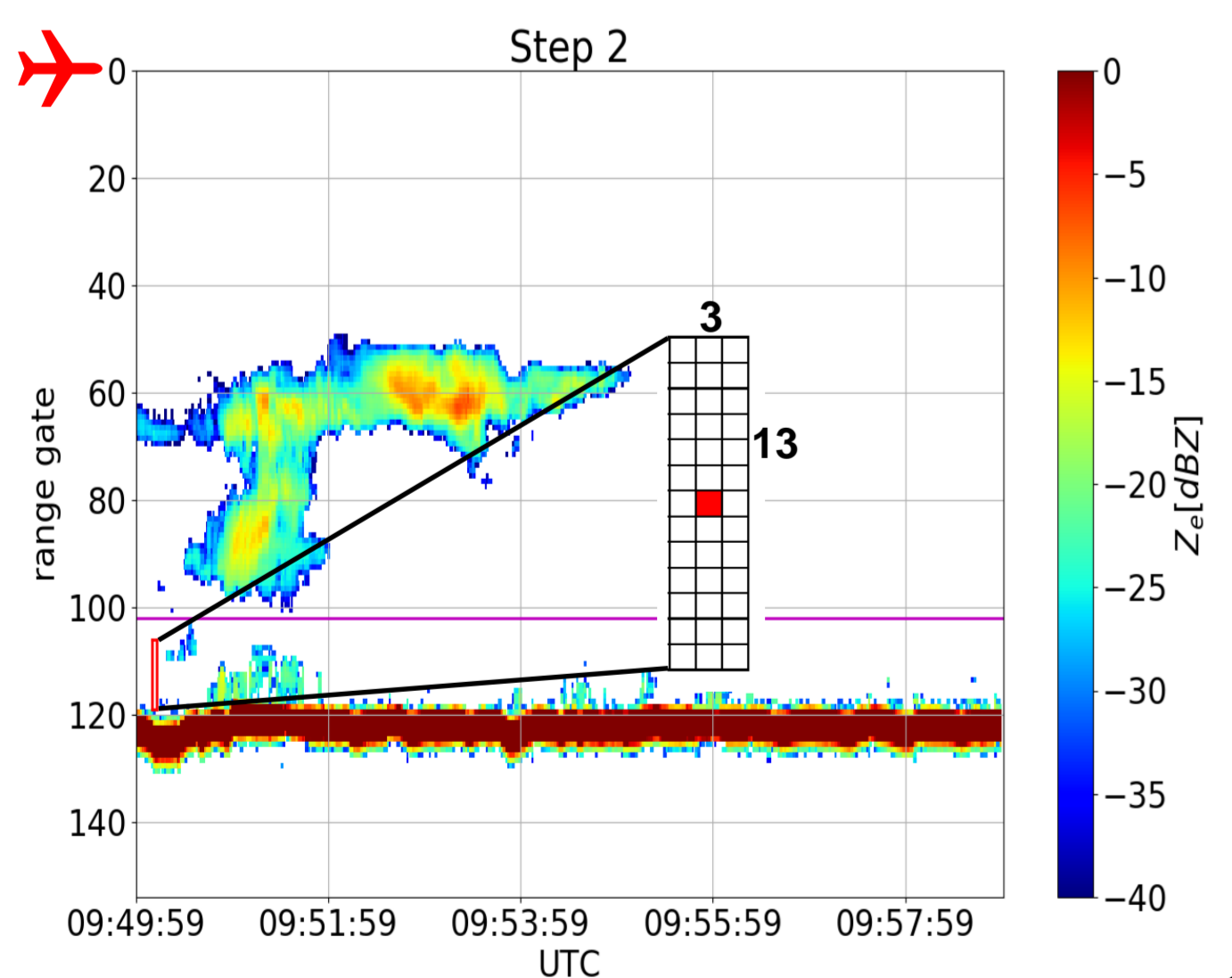


The raw data of Z consist of range gates with a length of 18 to 27 m as a function of distance from the aircraft.

I. Strong Surface echo leaks into range gates further away from the surface:



A threshold is used to exclude reflectivities below the sensitivity level. Another threshold is used to exclude radar processor artifacts (not shown).



II. Speckle filter removes noisy signals:

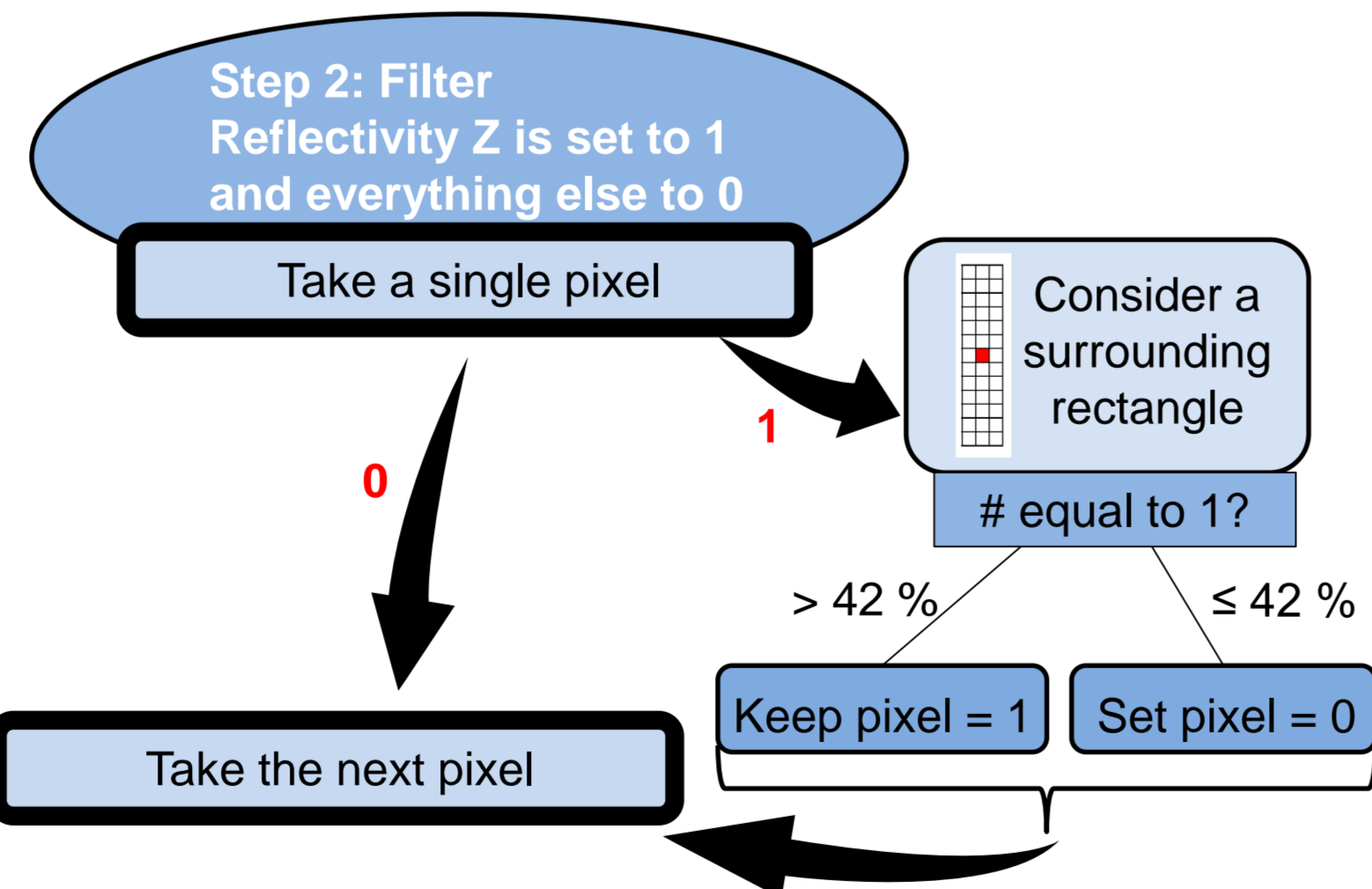
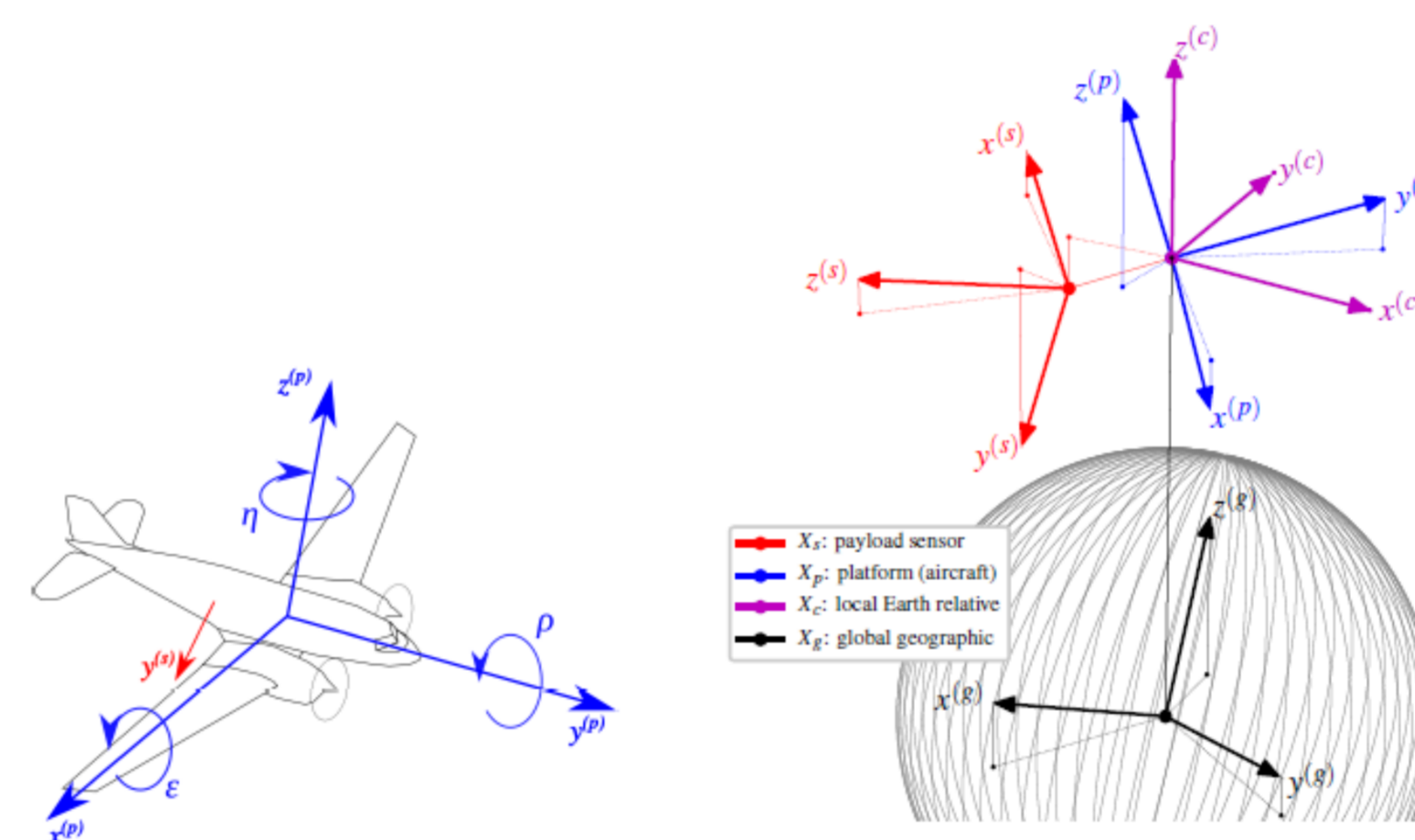


Fig. 2: Radar reflectivity May 25, 2017, flight 5, Top: raw data, Center: Step 1 mirror image bottom: Step 2 filter below magenta line

Coordinate transformations



- A calibration provides the exact position and attitude of the sensor within the aircraft.
- The data are transformed from the sensor-relative coordinate system via the platform- and local Earth relative coordinate system to the global geographic coordinate system.
- The data are mapped onto a constant vertical grid.

Resulting profiles and Ny-Ålesund overflight

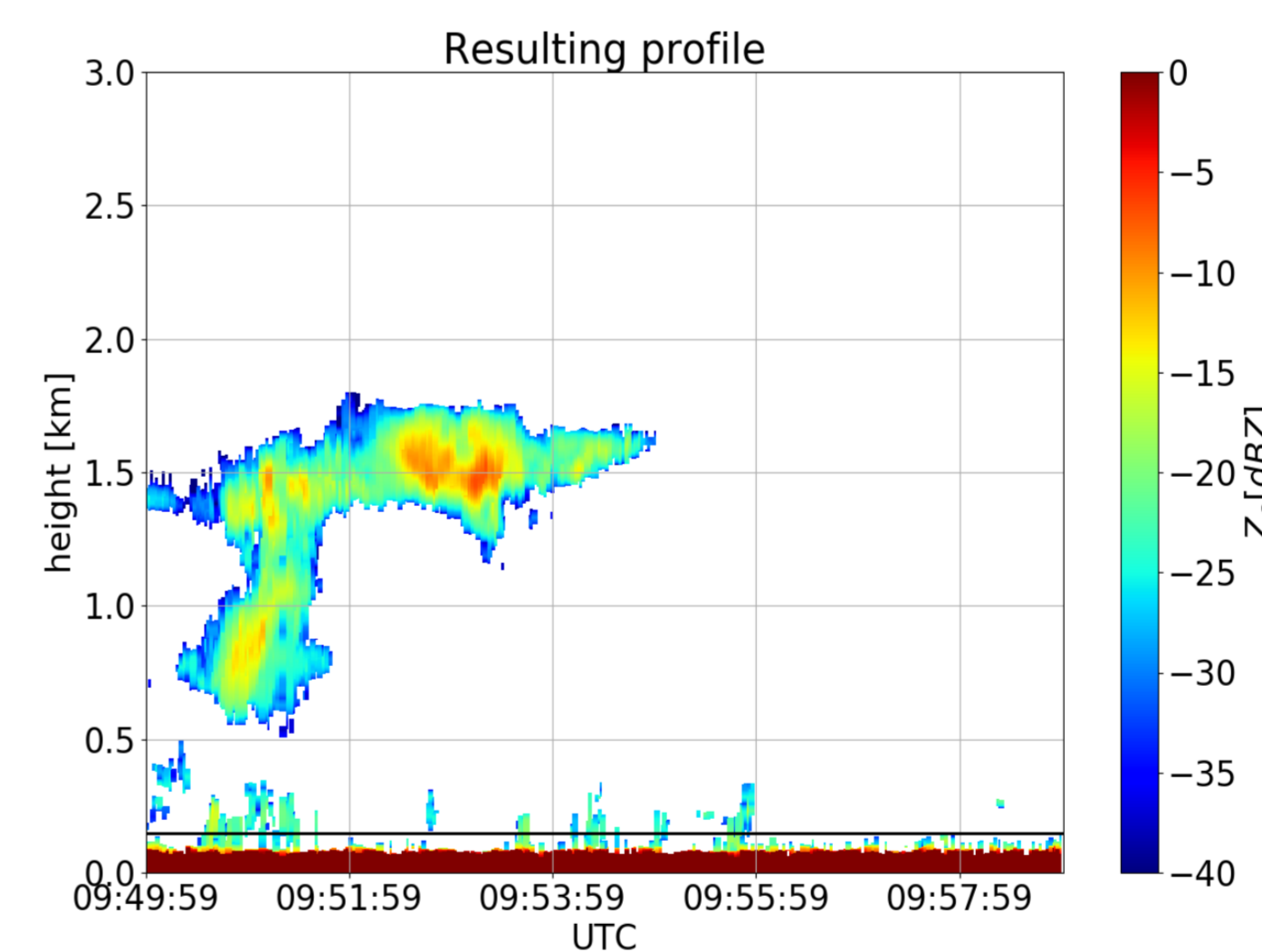


Fig. 4: Radar reflectivity May 25, 2017, corrected and transformed coordinates: Step 1 & 2, coordinate transformation and remapping, **black line:** 150 m

Surface influence:
For cloud analyses a height above 150 m is recommended. Everything below 150 m is considered to be strongly influenced by the surface. This will be indicated by a flag.

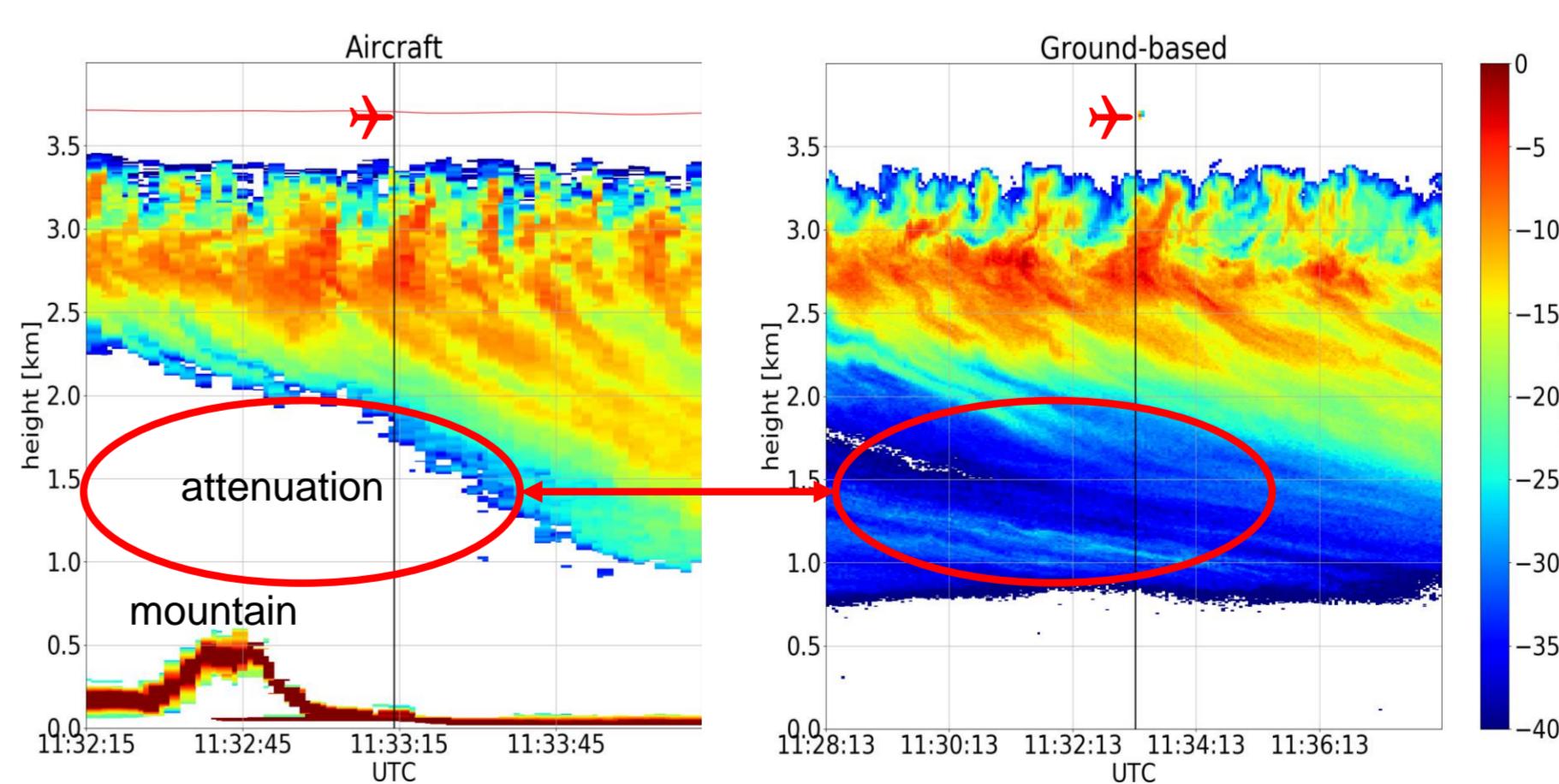


Fig. 5: Flight over Ny-Ålesund (left), Ground-based JOYRAD-94 (right). **Black line** indicates overflight. Flight 22, 2017/06/23

Comparison MiRAC and JOYRAD-94:

Measurements can differ strongly due to

- The different perspective from above or below the cloud (attenuation).
- The perspective of MiRAC inclined by 25° .
- The surrounding wind conditions.

Outlook

- In total measurements of 77.5 h are available. About 40.5 h (~ 52 %) are straight and horizontally oriented.
- The next step is to analyze the changes due to the correction process and to include quality flags to assign uncertainty levels of the measurements.
- The surface reflectivity will also be used to distinguish between land, ice and ocean.

Following milestones:

- Upload corrected radar reflectivity into the database PANGAEA.
- Develop LWP retrieval algorithm from T_B .
- Derive cloud and precipitation properties.

Reference:

N. Kuechler, S. Kneifel, U. Loehnert, P. Kollias, H. Czekala, and T. Rose. A W-Band Radar/Radiometer System for Accurate and Continuous Monitoring of Clouds and Precipitation. *Journal of Atmospheric and Oceanic Technology*, 34:23752392, 2017. doi:10.1175/JTECH-D-17-0019.1.